CLAIMS

1. An apparatus for manipulating an elastomer ball, comprising:

an elongate shaft having a grip end and a lower end; and

a head assembly affixed to the lower end of the shaft, the golf assembly comprising:

a face having a generally planar surface at an angle with respect to the shaft;

a back surface adjacent the face, the back surface having an opening to a pocket cavity;

and

the pocket cavity formed within an interior region defined by the face, the back surface, and a bottom portion connecting the face to the back surface, the pocket cavity having a first region for securely storing the ball, and a second region for at least one of catching, scooping up, and tossing the ball.

2. The apparatus of Claim 1, wherein the angle is 60 degrees.

3. The apparatus of Claim 1, wherein the shaft comprises means for adjusting the angle of the face.

4. An apparatus for striking, scooping, tossing and storing an elastomer ball, the apparatus comprising:

a shaft having a first end for gripping of the apparatus;

a striking head attached to a second end of the shaft, the striking head including:

a striking surface positioned at an angle with respect to the shaft, wherein the striking surface is substantially parallel to a horizontal ground plane when the user grips the first end of the shaft;

a back surface adjacent the striking surface, the back surface comprising an opening to a pocket;

a bottom surface connecting the striking surface to the back surface; and

the pocket forming an enclosed area defined by a region between the striking surface, the back surface and the bottom surface, the pocket accessible through the opening in the back surface, and the pocket having a first region for securely storing the ball, and a second region for loosely carrying the ball.

5. The apparatus as in Claim 4, wherein the shaft further comprises a hinging point for adjusting the angle of the striking surface.

6. An apparatus for manipulating an elastomer ball, comprising:

an elongate shaft having a longitudinal axis, a proximal end and a distal end;

a gripping surface at the proximal end of the elongate shaft;

a head assembly fixedly attached to the distal end of the elongate shaft, the head assembly comprising:

a face adapted for bouncing the elastomer ball in a substantially vertical direction, the face comprising a substantially planar surface at an angle with respect to the longitudinal axis of the elongate shaft;

a back surface, positioned adjacent the face and a bottom surface, containing a cavity of substantially constant depth at least as great as the radius of the elastomer ball, the cavity adapted for at least one of catching, scooping, tossing and storing the elastomer ball, the cavity comprising:

a substantially flat cavity bottom;

a substantially flat sidewall portion approximately perpendicular to the cavity bottom; and

a curvilinear sidewall portion approximately perpendicular to the cavity bottom, wherein the curvilinear sidewall portion defines a first and second region,

the first region adapted for at least one of catching, scooping and tossing the elastomer ball, wherein the distance between the substantially flat sidewall portion and the curvilinear sidewall portion is greater than the diameter of the elastomer ball; and

a second region, adjacent to the first region, adapted for storing the elastomer ball, wherein the distance between the substantially flat sidewall portion and the curvilinear sidewall portion is less than the diameter of the elastomer ball.

7. The apparatus as in Claim 6, wherein the first region is contiguous with the second region.

8. A method for manipulating an elastomer ball with an assembly that is fixedly attached to the distal end of an elongate shaft, comprising the steps of:

gripping the proximal end of the elongate shaft;

storing the elastomer ball in a first region of an assembly cavity, the first region adapted to retain the elastomer ball by compression;

retrieving the elastomer ball from the first region of the cavity;

bouncing the elastomer ball on a face of the assembly in a substantially vertical direction;

catching the elastomer ball in a second region of the assembly cavity, the second region adapted to loosely contain the elastomer ball;

serving the elastomer ball from the second region of the cavity; and

scooping the elastomer ball from the ground into the second region of the cavity as necessary.

9. The method of Claim 8, wherein the step of serving the elastomer ball from the second region of the assembly cavity comprises serving to at least one of the face or second region of the assembly.

10. The method of Claim 8, wherein the step of serving the elastomer ball comprises serving to an apparatus of a second user.

11. The method of Claim 8, wherein the step of serving the elastomer ball comprises serving to a rebounding surface.

12. The method of Claim 8, wherein the step of bouncing the elastomer ball on a face of the assembly comprises directing the elastomer ball to at least one of the face or second region of a second apparatus of a second user.